

# Signal Processing

The [SignalProcessing](#) package has been expanded with new and updated commands.

```
> restart;
```

## ▼ SignalProcessing

```
> with( SignalProcessing ):
```

### ▼ GenerateSignal

The new [GenerateSignal](#) command is useful for creating signals, filters, and windows from algebraic expressions. For example:

```
> X := GenerateSignal( 3 * sin(t) + cos(2*t), t = 0 .. 4 * Pi, 100
);
```

$$X := \begin{bmatrix} 1. \\ 1.34772606211760 \\ 1.62729333861302 \\ 1.83872140508605 \\ 1.98581567591191 \\ 2.07564416249220 \\ 2.11781895027008 \\ 2.12363272481008 \\ 2.10510967724277 \\ 2.07403525211827 \\ \vdots \end{bmatrix}$$

100 element Vector[column]

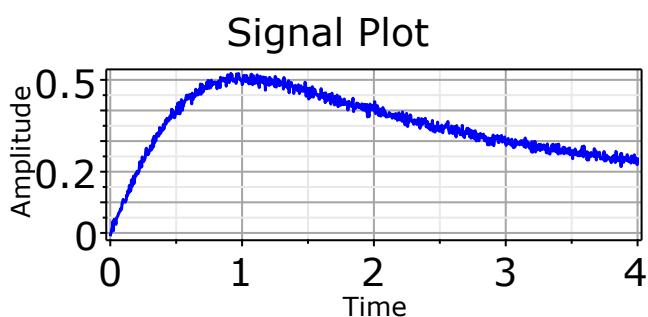
The command also packages many related features and data for the signal:

```
> sample_rate, Times, Signal := GenerateSignal( t * exp(-t), t = 0 .. 5, 10^3, 'output' = ['samplerate','times','signal'] );
```

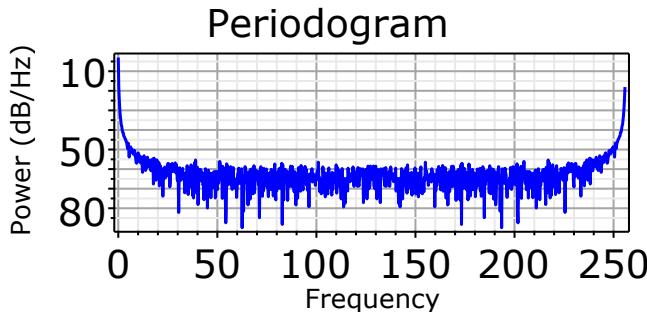
```
sample_rate, Times, Signal := 199.800000000000011,
[ 0.
  0.00500500500500500
  0.0100100100100100
  0.0150150150150150
  0.0200200200200200
  0.0250250250250250
  0.0300300300300300
  0.0350350350350350
  0.0400400400400400
  0.0450450450450450
  :
  ],
1000 element Vector[column]
```

```
[ 0.
  0.00498001751332686
  0.00991030954344368
  0.0147912484721253
  0.0196232042023248
  0.0244065441736429
  0.0291416333777046
  0.0338288343734441
  0.0384685073022971
  0.0430610099033036
  :
  ],
1000 element Vector[column]
```

```
> R := GenerateSignal( t / (1+t^2), t = 0 .. 4, 2^10, 'noisetype' =
  'additive', 'noisedeviation' = 0.01, 'output' = 'record' );
> R['signalplot'];
```



```
> R['periodogram'];
```



## ▼ DynamicTimeWarping

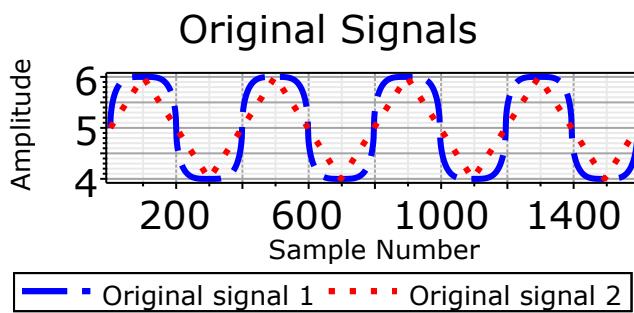
The [DynamicTimeWarping](#) command, which has many applications including speech recognition and genetic sequencing, determines the best match between two signals by varying the sampling rates dynamically. For example:

```
> X := GenerateSignal( 5 + sqrt(1-(t-1)^4), t = 0 .. 2, 200,
  'mirror' = 'antisymmetric', 'copies' = 4 ):

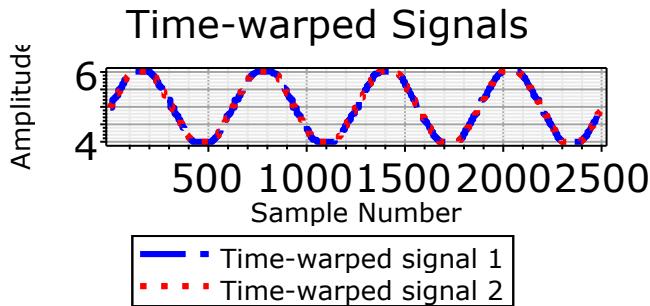
> Y := GenerateSignal( 6 - abs(t-1), t = 0 .. 2, 200, 'mirror' =
  'antisymmetric', 'copies' = 4 ):

> R := DynamicTimeWarping( X, Y, 'compiled', 'output' = 'record' ):

> R['unwarpedplot'];
```



```
> R['warpedplot'];
```



The match is computed by inserting zero or more copies of each sample for both signals in such a way that the cost with respect to the metric (taxicab, by default) is minimal.

For this example:

```
> R['cost'];
28.7505811441736654
```

In terms of the root mean square error:

```
> R['rmse'];
0.0220493272388582497
```

## ▼ DifferentiateData

The new [DifferentiateData](#) command offers the standard methods, namely Backward, Central, and Forward Difference, and also features spectral differentiation. For example:

```
> f := piecewise( t < Pi or t > 3 * Pi, sin(4*t) + 5, 1/10 * sin(40*t) + 5 );
a, b := 0, 4 * Pi;
n := 2^14;

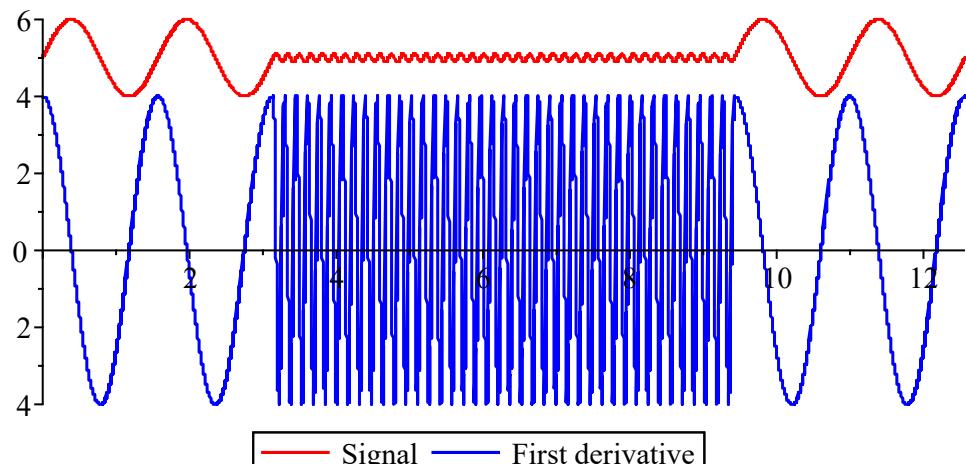

$$f := \begin{cases} \sin(4t) + 5 & t < \pi \text{ or } 3\pi < t \\ \frac{\sin(40t)}{10} + 5 & \text{otherwise} \end{cases}$$

a, b := 0, 4π
n := 16384

> ( dt, T, X ) := GenerateSignal( f, t = a .. b, n,
  'includefinishtime' = 'false', 'output' = ['timestep','times',
  'signal'] ):

> DX := DifferentiateData( X, 1, 'step' = dt, 'method' =
  'spectral', 'extrapolation' = 'periodic' ):

> dataplot( T, [X,DX], 'style' = 'line', 'color' = ['red','blue'],
  'legend' = ["Signal","First derivative"], 'size' = [500,250] );
```



## ▼ IntegrateData and IntegrateData2D

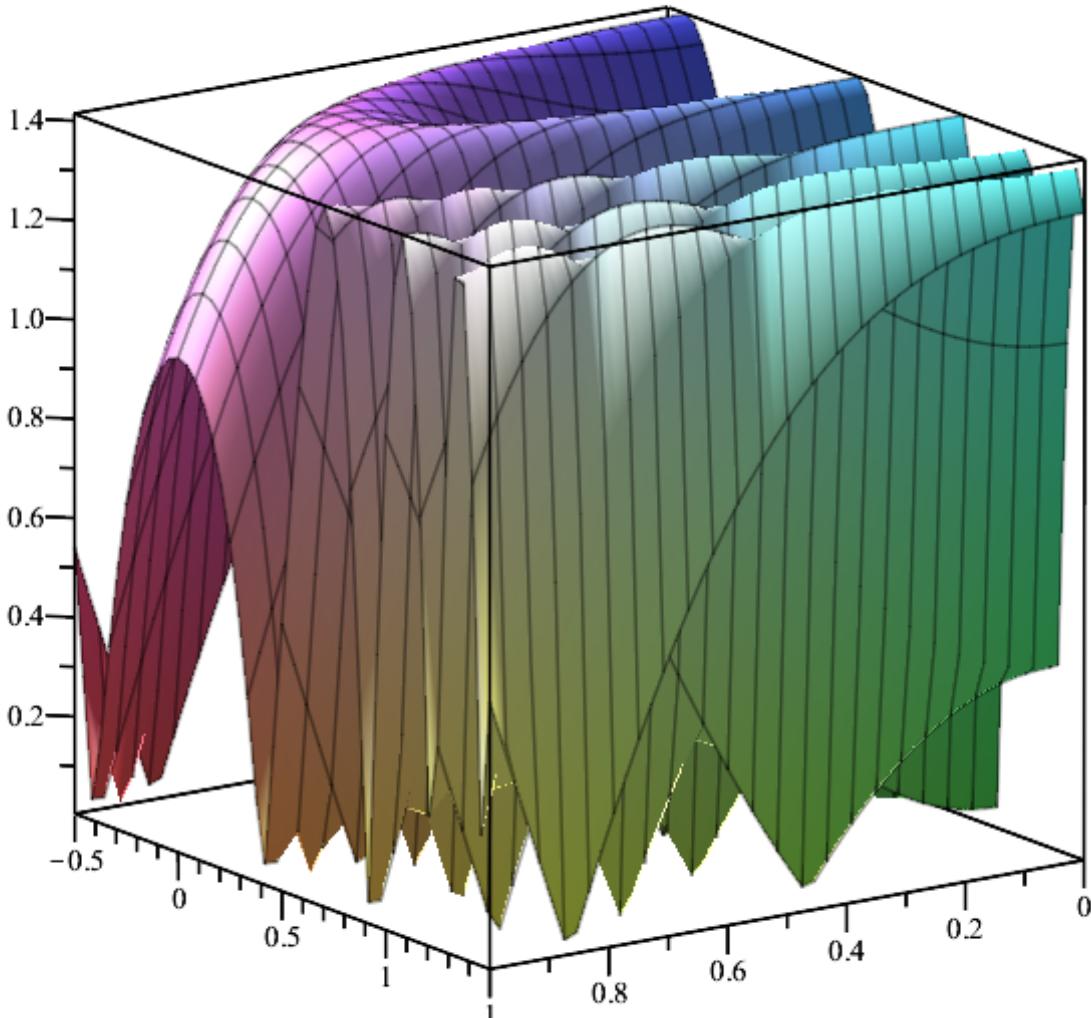
The [IntegrateData2D](#) command provides a fast and accurate way of finding the volume under a two-dimensional dataset. For example:

```
> f := (x,y) -> sqrt( 1 + sin( Pi * ( x^2 + 3 * y^2 ) ) );
  a, b, c, d := 0.0, 1.0, -0.5, 1.5;

$$f := (x, y) \rightarrow \sqrt{1 + \sin(\pi \cdot (x^2 + 3 \cdot y^2))}$$


$$a, b, c, d := 0., 1.0, -0.5, 1.5$$

> plot3d( f, a .. b, c .. d );
```



```
> m, n := 100, 100;
  dx, dy := evalhf( (b-a) / (m-1) ), evalhf( (d-c) / (n-1) );

$$m, n := 100, 100$$


$$dx, dy := 0.01010101010101019, 0.0202020202020202037$$

```

```

> X := Vector( m, i -> evalhf( a + (i-1) * dx ), 'datatype' =
  'float[8]' ):
Y := Vector( n, j -> evalhf( c + (j-1) * dy ), 'datatype' =
  'float[8]' ):
Z := Matrix( m, n, (i,j) -> evalhf( f( X[i], Y[j] ) ), 'datatype'
= 'float[8]' );

      1.30656296487638 1.30656296487638 1.30656296487638 1.30656296487638 1.30656296487638 1.30656296487638 1.30656296487638
      1.35122406134324 1.35122406134324 1.35122406134324 1.35122406134324 1.35122406134324 1.35122406134324 1.35122406134324
      1.38295754218013 1.38295754218013 1.38295754218013 1.38295754218013 1.38295754218013 1.38295754218013 1.38295754218013
      1.40302880476168 1.40302880476168 1.40302880476168 1.40302880476168 1.40302880476168 1.40302880476168 1.40302880476168
      1.41276686457614 1.41276686457614 1.41276686457614 1.41276686457614 1.41276686457614 1.41276686457614 1.41276686457614
      1.41352474569771 1.41352474569771 1.41352474569771 1.41352474569771 1.41352474569771 1.41352474569771 1.41352474569771
      1.40664653803368 1.40664653803368 1.40664653803368 1.40664653803368 1.40664653803368 1.40664653803368 1.40664653803368
      1.39344080846178 1.39344080846178 1.39344080846178 1.39344080846178 1.39344080846178 1.39344080846178 1.39344080846178
      1.37515989082796 1.37515989082796 1.37515989082796 1.37515989082796 1.37515989082796 1.37515989082796 1.37515989082796
      1.35298447186640 1.35298447186640 1.35298447186640 1.35298447186640 1.35298447186640 1.35298447186640 1.35298447186640
      :           :           :           :           :           :           :

```

```

> IntegrateData2D( X, Y, Z, 'uniform', 'compiled', 'method' =
  'simpson' );

```

2.09312887784632640

This command supports both uniform (regular) and non-uniform (irregular) data. The option **uniform** tells the algorithm to skip the check for uniformity and use the uniform version of Simpson's Rule, which is quicker. The existing (added in Maple 2021) one-dimensional version of the command, [IntegrateData](#), has been updated to include the **compiled** and **uniform** options.

## ▼ RealPart and ImaginaryPart

The new [RealPart](#) and [ImaginaryPart](#) commands complement the existing [ComplexToReal](#) command. They, respectively, take a **complex[8]** container and quickly create a **float[8]** container for the real part and imaginary part.

For example:

```
> X := LinearAlgebra:-RandomVector( 5, 'generator' = -1.0 - 1.0 * I
.. 1.0 + 1.0 * I, 'datatype' = 'complex[8]' );
X := 
$$\begin{bmatrix} -0.170954922213783 - 0.0703201167497254 \text{I} \\ 0.998983240195409 - 0.424301310369726 \text{I} \\ 0.0799641980758583 + 0.413834838645526 \text{I} \\ -0.763689603106579 + 0.976835857569961 \text{I} \\ -0.338342009593391 + 0.796972275668599 \text{I} \end{bmatrix}$$

> Y := RealPart( X );
Y := 
$$\begin{bmatrix} -0.170954922213783 \\ 0.998983240195409 \\ 0.0799641980758583 \\ -0.763689603106579 \\ -0.338342009593391 \end{bmatrix}$$

> Z := ImaginaryPart( X );
Z := 
$$\begin{bmatrix} -0.0703201167497254 \\ -0.424301310369726 \\ 0.413834838645526 \\ 0.976835857569961 \\ 0.796972275668599 \end{bmatrix}$$

```

Of course, if you need both the real and imaginary parts, it is best to use the **ComplexToReal** command:

```
> ComplexToReal( X );

$$\begin{bmatrix} -0.170954922213783 \\ 0.998983240195409 \\ 0.0799641980758583 \\ -0.763689603106579 \\ -0.338342009593391 \end{bmatrix}, \begin{bmatrix} -0.0703201167497254 \\ -0.424301310369726 \\ 0.413834838645526 \\ 0.976835857569961 \\ 0.796972275668599 \end{bmatrix}$$

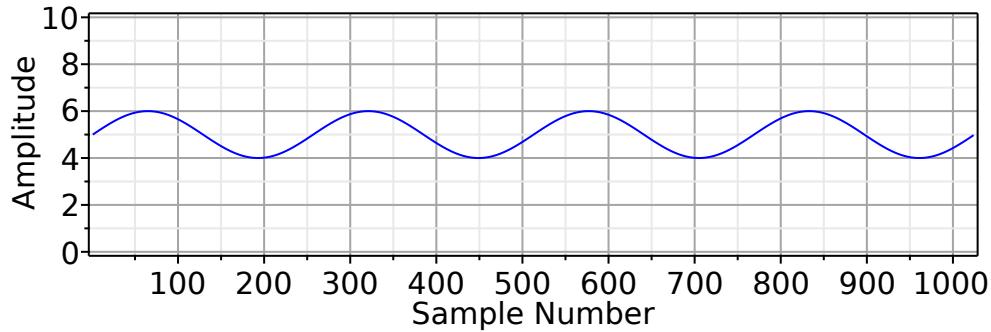
```

## ▼ Insert

The new [Insert](#) command can take one signal, and insert it into another at any point. For example:

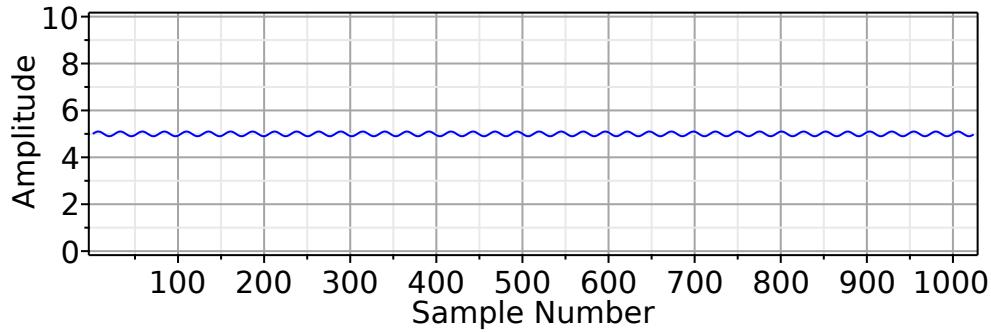
```
> n := 2^10;
n := 1024
> X := GenerateSignal( sin(4*t) + 5, t = 0 .. 2 * Pi, n,
'includefinishtime' = 'false' );
```

```
> SignalPlot( X, 'view' = [ 'DEFAULT',0..10], 'color' = 'blue' );
```



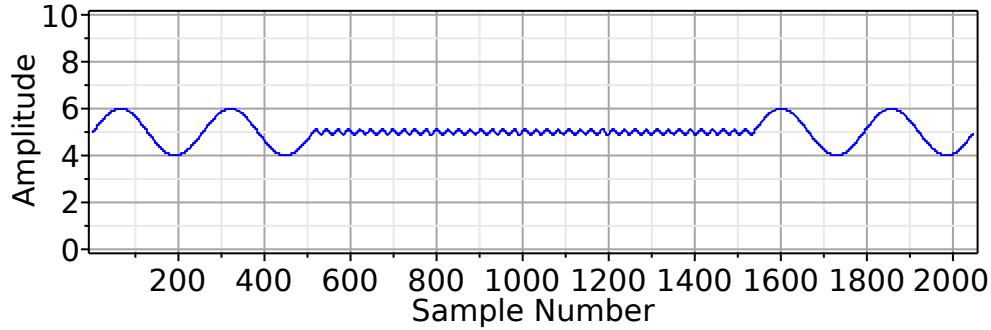
```
> Y := GenerateSignal( 1/10 * sin(40*t) + 5, t = 0 .. 2 * Pi, n,
  'includefinishtime' = 'false' );
```

```
> SignalPlot( Y, 'view' = [ 'DEFAULT',0..10], 'color' = 'blue' );
```



```
> Insert( X, floor(n/2) + 1, Y, 'inplace' );
```

```
> SignalPlot( X, 'view' = [ 'DEFAULT',0..10], 'color' = 'blue' );
```



## ▼ FindPeakPoints

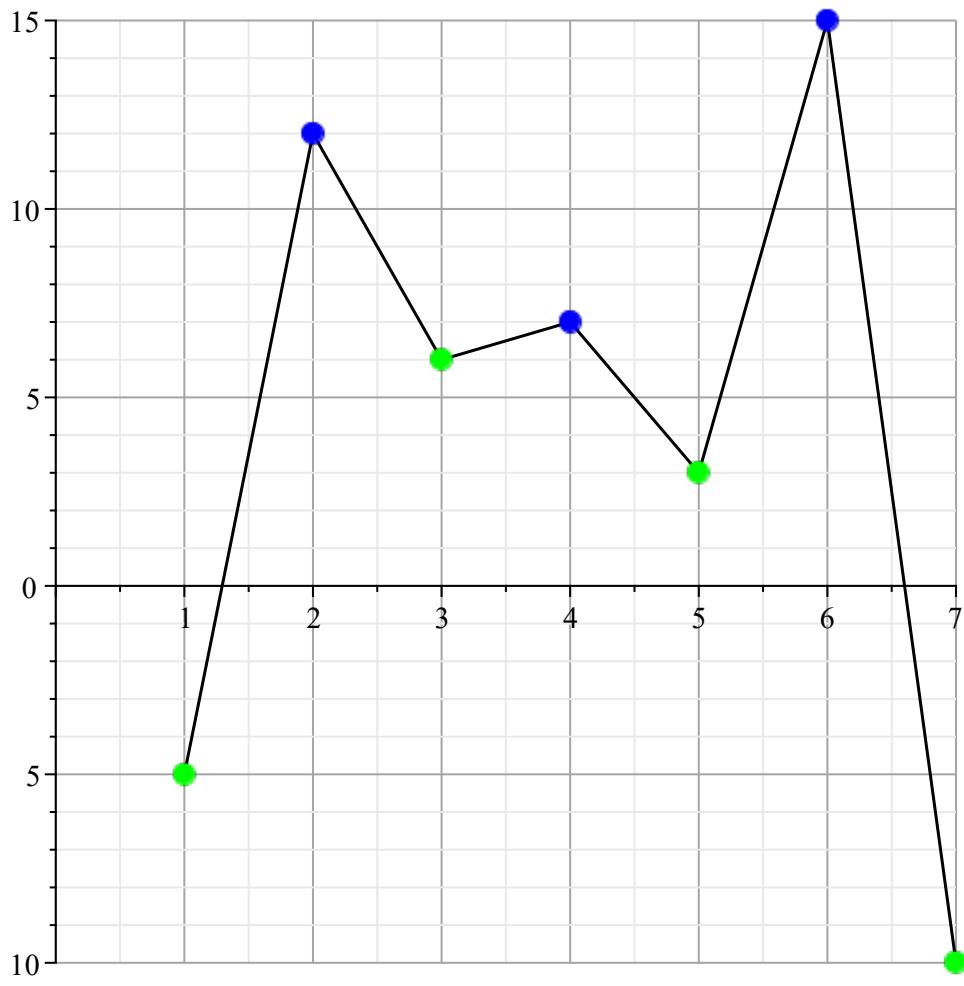
The [FindPeakPoints](#) command now has output options for the indices of the peaks and valleys.

For example:

```
> X := < -5, 12, 6, 7, 3, 15, -10 >;
```

$$X := \begin{bmatrix} -5 \\ 12 \\ 6 \\ 7 \\ 3 \\ 15 \\ -10 \end{bmatrix}$$

```
> FindPeakPoints( X, 'output' = 'plot', 'plotincludepoints' =  
['peaks','regular','valleys'], 'gridlines' );
```



```
> FindPeakPoints( X, 'output' = [ 'peakindices', 'valleyindices' ] );
```

$$\begin{bmatrix} 2 \\ 4 \\ 6 \end{bmatrix}, \begin{bmatrix} 1 \\ 3 \\ 5 \\ 7 \end{bmatrix}$$

## ▼ RootMeanSquareError and RelativeRootMeanSquareError

The [RootMeanSquareError](#) and [RelativeRootMeanSquareError](#) commands have been sped up for large data containers. For example:

```
> n := 10^5;
  r := 1.0 + 1.0 * I;
  dt := 'complex[8]';
  X := LinearAlgebra:-RandomVector( n, 'generator' = -r .. r,
  'datatype' = dt );
  Y := LinearAlgebra:-RandomVector( n, 'generator' = -r .. r,
  'datatype' = dt );
  n := 100000
  r := 1.0 + I
  dt := complex8

> tests := 25;
  CodeTools:-Usage( RootMeanSquareError( X, Y ), 'iterations' =
  tests );
  CodeTools:-Usage( RelativeRootMeanSquareError( X, Y ),
  'iterations' = tests );
  tests := 25
memory used=16.36KiB, alloc change=0 bytes, cpu time=3.12ms, real
time=3.56ms, gc time=0ns

  1.15349306481481761
memory used=44.40KiB, alloc change=0 bytes, cpu time=7.48ms, real
time=7.20ms, gc time=0ns

  1.41397255876189520
```